

(2)

$$\left. \begin{aligned} \textcircled{1} \quad V &= r \dot{\lambda}_1 + \frac{1}{C} \int \lambda_3 dt \\ \textcircled{2} \quad 0 &= R \dot{\lambda}_2 + \frac{1}{C} \int \dot{\lambda}_3 dt \end{aligned} \right\}$$

$$\textcircled{3} \quad \lambda_1 + \lambda_2 = \dot{\lambda}_3$$

$$\frac{V - \frac{1}{C} \int \dot{\lambda}_3 dt}{r} \rightarrow \dot{\lambda}_1$$

$$\dot{i}_2 = \frac{-1}{RC} \int i_3 dt$$

$$\frac{v - \frac{1}{C} \int i_3 dt}{r} - \frac{1}{RC} \int i_3 dt = \dot{i}_3$$

$$i_3 = \frac{dq}{dt} \rightarrow$$

$$\frac{v}{r} - \frac{1}{rC} \int \frac{dq}{dt} dt - \frac{1}{RC} \int \frac{dq}{dt} dt = \frac{dq}{dt}$$

$$\frac{v}{r} - \frac{1}{rC} q(t) - \frac{1}{RC} q(t) = \frac{dq(t)}{dt}$$

$$\textcircled{q(t)} = CV \leftarrow V_C = 0$$

$$\frac{V}{r} - q(t) \left( \frac{1}{rC} + \frac{1}{RC} \right) = \frac{dq(t)}{dt}$$

$$\frac{dq(t)}{dt} + q(t) \left( \frac{1}{rC} + \frac{1}{RC} \right) = \boxed{\phantom{0}} \begin{matrix} \nearrow 0 \\ \downarrow \neq 0 \end{matrix}$$

= 特殊解 + 非同次的一般解

定常解  $\frac{dq}{dt} = 0$

$$\frac{dq(t)}{dt} + q(t) \left( \frac{1}{rC} + \frac{1}{RC} \right) = \frac{V}{r} = 0 \begin{matrix} \nearrow V=0 \\ \downarrow \end{matrix}$$

$$\frac{dq(t)}{dt} = - \left( \frac{1}{rC} + \frac{1}{RC} \right) q(t)$$

$$\left( \frac{R+r}{rCR} \right) \rightarrow q(t) = C_1 e^{-\frac{R+r}{rCR} t}$$

$$\int \frac{dq(t)}{q(t)} = \int - \left( \frac{R+r}{rCR} \right) dt$$

$$\boxed{\log_e |q(t)|} = - \frac{R+r}{rCR} t + A$$

~~$e^{\log(q(t))} = q(t)$~~ 
 $q(t) = e^{-\frac{R+r}{rCR} t + A}$

~~$e^{-\frac{R+r}{rCR} t} \cdot e^A$~~

$q(t) = C_1 e^{-\frac{R+r}{rCR} t}$

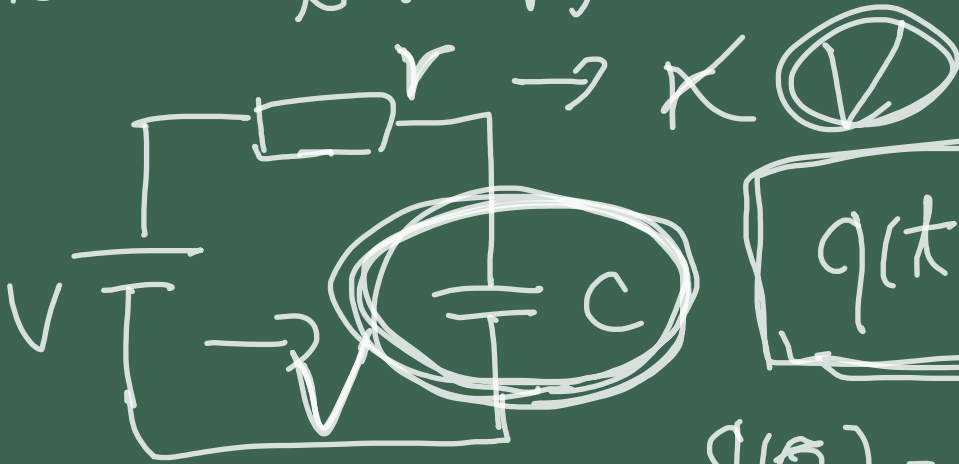
$C_1$

$$\frac{V}{s} = +q(s) \left( \frac{r+R}{sCR} \right)$$

$$q(s) = \frac{CR}{r+R} V$$

$$q(s) = \frac{CR}{r+R} V + \boxed{C_1} e^{-\frac{r+R}{rCR} t}$$

$t=0$   $S$  が閉じたときの定常



$$q(t) = CV$$

$$q(0) = CV$$

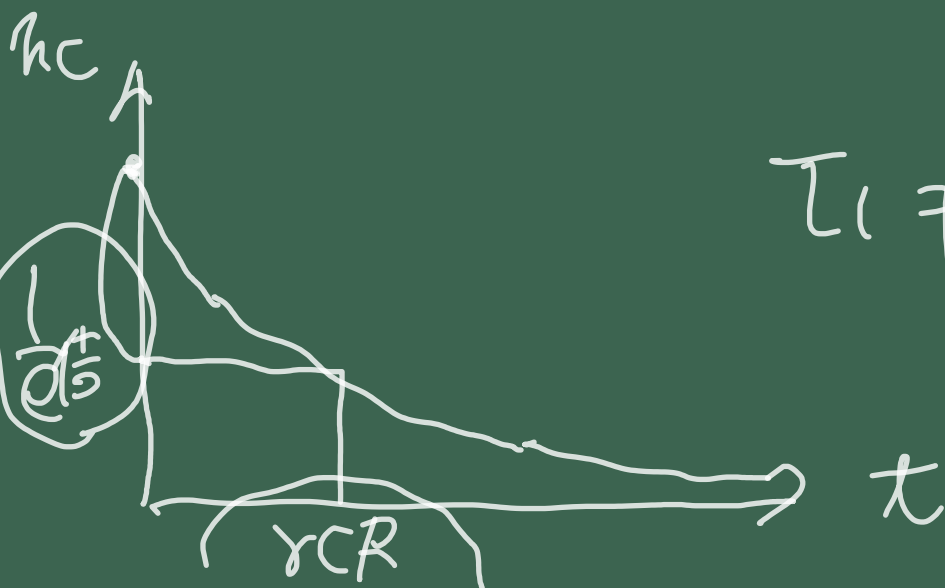
$$CV = \frac{CR}{r+R} V + C_1 e^{-\frac{r+R}{rCR} t}$$

$$C_1 = \left( CV - \frac{CR}{r+R} V \right) \exp\left(\frac{r+R}{rCR} t\right)$$

$$q(t) = \frac{CR}{r+R} V + CV \left(1 - \frac{R}{r+R}\right) \exp\left(-\frac{r+R}{rCR} t\right)$$

$$n_c(t) \rightarrow Q = CV \quad V = \frac{Q}{C}$$

$$n_c(t) = \frac{R}{r+R} V + \left\{ V \left(1 - \frac{R}{r+R}\right) \exp\left(-\frac{r+R}{rCR} t\right) \right\}$$



$$\tau_1 = \frac{rCR}{r+R}$$

$$\overline{(r+R)}$$



$$V = r i + \frac{1}{C} \int i dt$$

~~$$V = r \frac{dq(t)}{dt} + \frac{1}{C} q(t)$$~~

$$i = \frac{dq(t)}{dt}$$

$$V = r \frac{dq(t)}{dt} + \frac{1}{C} q(t)$$

$$- \frac{q(t)}{rC} = \frac{dq(t)}{dt}$$

$$q(t) = A e^{-\frac{t}{rC}}$$

积分常数

→ 过渡  
三波  
解

$$\frac{q(t)}{C} = V \quad q(t) = CV$$

$$q(t) = CV + A e^{-\frac{1}{rc}t}$$

$$t = t_0 \quad q(t_0) = \frac{CR}{r+R} V$$

$$\frac{CR}{r+R} V = CV + A e^{-\frac{1}{rc}t}$$

$$A = -\frac{CR}{r+R} V e^{\frac{1}{rc}t_0}$$



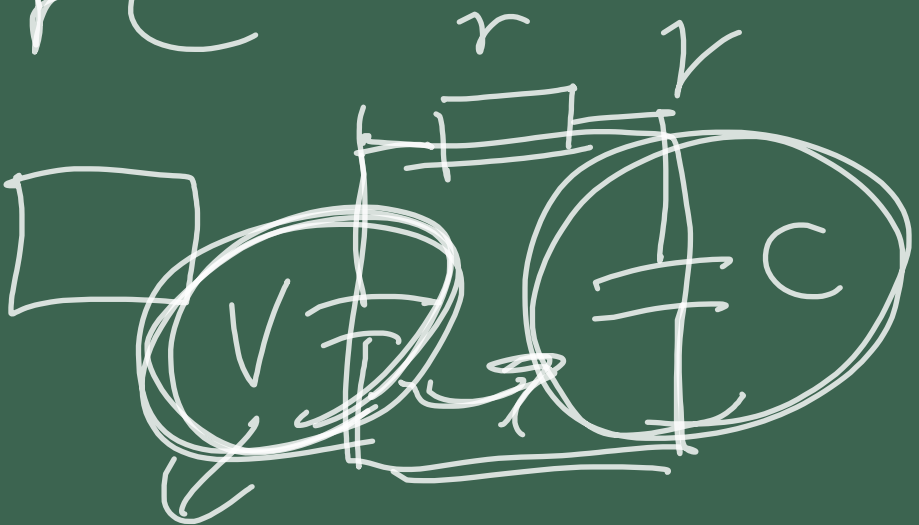
$$q(t) = CV - \frac{Cr}{r+R} V e^{\frac{1}{rc}t_0} e^{-\frac{1}{rc}t}$$

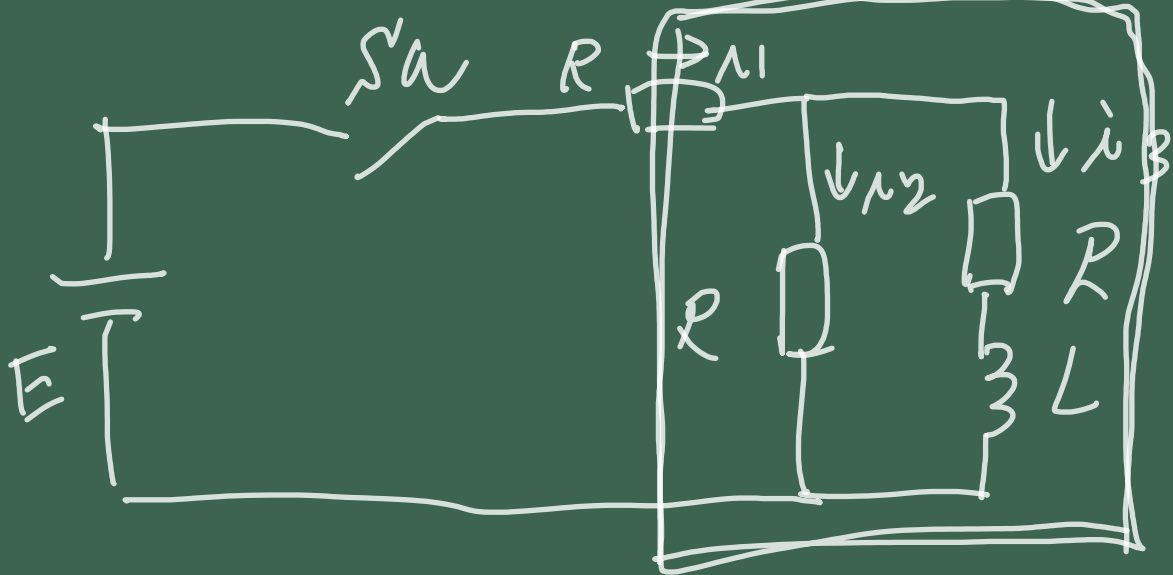
$$= CV - \frac{Cr}{r+R} V e^{-\frac{1}{rc}(t-t_0)}$$

$$n_c(t) = \frac{q(t)}{C} = \left( V - \frac{Cr}{r+R} V e^{-\frac{1}{rc}(t-t_0)} \right)$$

$$T_2 = rC$$

$$t \Rightarrow \infty$$





$t < 0$   
 $S$  is OFF  
 $t \geq 0$   
 $S$  is ON

$$i_1 = i_2 + i_3 \quad (1)$$

$$R i_2 = R i_3 + L \frac{d i_3}{d t} \quad (2)$$

$$E = R i_1 + R i_2 \quad (3)$$

~~$$\frac{E - R i_2}{R} = i_1$$~~

$$\frac{E - R i_2}{R} = i_2 + i_3 \quad i =$$

$$\frac{E}{R} - i_2 = i_2 + i_3$$

$$\frac{E}{R} - 2 i_2 = i_3$$

$$\frac{E}{2R} - \frac{i_3}{2} = i_2$$

$$\dot{\lambda}_1 = \frac{2E}{2R} - \frac{E}{2R} + \frac{\dot{\lambda}_3}{2}$$

$$\dot{\lambda}_1 = \frac{1}{2R}E + \frac{\dot{\lambda}_3}{2}$$

$$R\dot{\lambda}_2 = \frac{E}{2} - \frac{R\dot{\lambda}_3}{2}$$

$$= R\dot{\lambda}_3 + L \frac{d\dot{\lambda}_3}{dt}$$

$$\frac{E}{2} = \frac{3}{2}R\dot{\lambda}_3 + \cancel{L} \frac{d\dot{\lambda}_3}{dt}$$

$$E = 3R\dot{\lambda}_3 + \cancel{\frac{2L}{2}} \frac{d\dot{\lambda}_3}{dt}$$

$$\cancel{\frac{d\dot{\lambda}_3}{dt}} = -\frac{3R\dot{\lambda}_3}{2L}$$

$$\dot{\lambda}_3 = \underline{C_1} e^{-\frac{3R}{2L}t}$$

$$\frac{d\dot{i}_3}{dt} = 0 \quad E = 3R\dot{i}_3 \quad \dot{i}_3 = \frac{E}{3R}$$

$$\dot{i}_3(t) = \frac{E}{3R} + C_1 e^{-\frac{3R}{2L}t}$$

$$\cancel{0} = \frac{E}{3R} + C_1 e^{-\frac{3R}{2L}t}$$

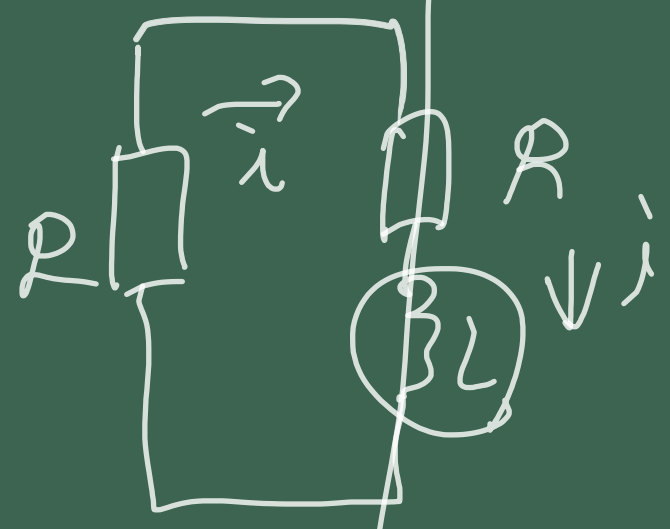
$$C_1 = -\frac{E}{3R} \begin{bmatrix} \frac{3R}{2L} & 0 \\ 0 & 1 \end{bmatrix} \rightarrow 1$$

$$C_1 = \frac{-E}{3R}$$

$$\dot{i}_3(t) = \frac{E}{3R} \left( 1 - e^{-\frac{3R}{2L}t} \right)$$

$$T_L = \frac{2L}{3R}$$

$$x_3(T) = \frac{E}{3R}$$



$$0 = 2Ri + L \frac{di}{dt}$$

$$-\frac{2R}{L}i = \frac{di}{dt}$$

$$i = C_1 e^{-\frac{2R}{L}t}$$

$$\frac{E}{3R} = C_1 e^{-\frac{2R}{L}t} \cdot t \rightarrow T$$

$$C_1 = \frac{E}{3R}$$

$$C_1 \frac{\cancel{E}}{3R} = \frac{E}{3R} e^{\frac{2R}{L}t}$$

$$i_3 = \frac{E}{3R} e^{-\frac{2R}{L}(t-T)}$$

$$(5) \left( \frac{L}{2R} \right)$$











