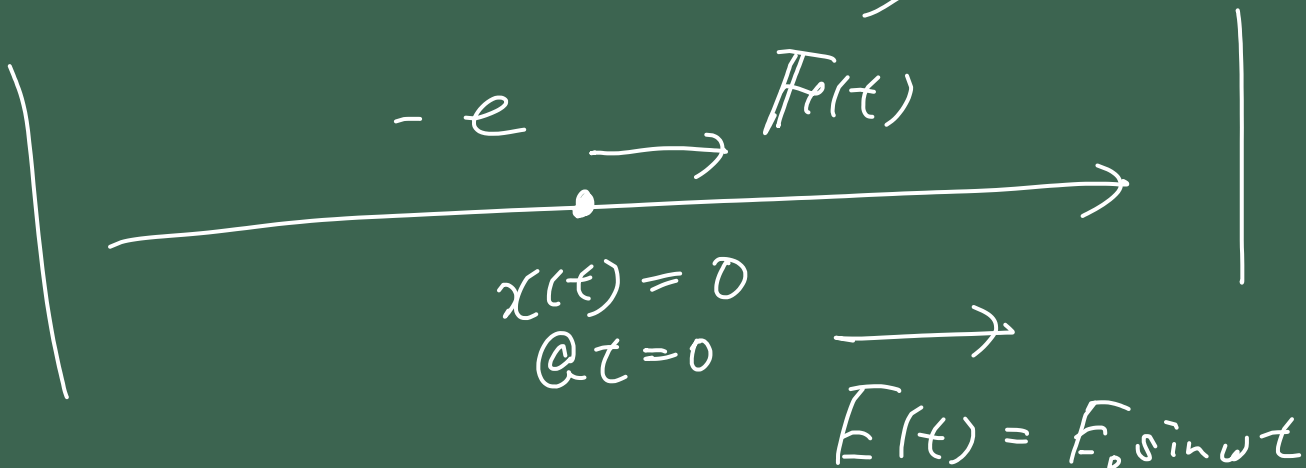


RS 126

$$(1) \quad \vec{F}(t) = \begin{pmatrix} F_x(t) \\ F_y(t) \\ F_z(t) \end{pmatrix} = \begin{pmatrix} F_x(t) \\ 0 \\ 0 \end{pmatrix}$$



$$\vec{E}(t) = \begin{pmatrix} E_x(t) \\ E_y(t) \\ E_z(t) \end{pmatrix} = \begin{pmatrix} E(t) \\ 0 \\ 0 \end{pmatrix}$$

$$\vec{F}(t) = q \vec{E}(t)$$

$$\begin{pmatrix} F_x(t) \\ F_y(t) = 0 \\ F_z(t) = 0 \end{pmatrix} = q \begin{pmatrix} E_x(t) \\ E_y(t) = 0 \\ E_z(t) = 0 \end{pmatrix}$$

$$\bar{F}_x(t) = q E_x(t)$$

$$F(t) = q E(t) \\ = q F_0 \sin \omega t$$

$$q = -e$$

$$\bar{F}(t) = -e F_0 \sin \omega t$$

||

(2)

$$F(t) = m \frac{dv}{dt}$$

\uparrow \uparrow \uparrow
 力 質量 $\frac{mv}{t}$ 加速度 $\frac{v}{t}$ $a = \frac{dv}{dt}$

$$-e E \sin \omega t = m \frac{dv}{dt}$$

(2) □

$$\frac{dv}{dt} = \frac{-e E}{m} \sin \omega t$$

← $v(t)$ 127120
127120

(3)

定積分

$$\frac{df(t)}{dt} = g(t)$$

$$\int_0^t \frac{df}{dt}(t) dt = \int_0^t g(t) dt$$

$$\left[f(t) \right]_0^t$$

$$f(t) - f(0) = \int_0^t g(t) dt$$

$$\int \sin \omega t dt = -\frac{1}{\omega} \cos \omega t + K$$

$$\left(-\frac{1}{\omega} \cos \omega t + K \right)' = -\frac{1}{\omega} (-\omega \sin \omega t) \\ = \sin \omega t$$

$$\int_a^b \sin \omega t dt = \left[-\frac{1}{\omega} \cos \omega t \right]_a^b \\ = -\frac{1}{\omega} (\cos \omega b - \cos \omega a)$$

$$\frac{dv}{dt} = -\frac{eE_0}{m} \sin \omega t$$

$$\int_0^t \frac{dv}{dt} dt = -\frac{eE_0}{m} \int_0^t \sin \omega t dt$$

$$v(t) - v_0 = -\frac{eE_0}{m} \left[-\frac{1}{\omega} \cos \omega t \right]_0^t$$

$$= +\frac{eE_0}{m\omega} [\cos \omega t]_0^t$$

$$= \frac{eE_0}{m\omega} (\cos \omega t - 1)$$

$$v(t) = v_0 + \frac{eE_0}{m\omega} (\cos \omega t - 1)$$

$$= v_0 - \left[\frac{eE_0}{m\omega} \right] (1 - \cos \omega t)$$

$$(\sin t)' = \cos t \quad (3) \quad \nabla$$

$$(\sin \omega t)' = \frac{d(\omega t)}{dt} \left(\frac{d}{d(\omega t)} \sin(\omega t) \right)$$

$$= \omega \cos \omega t$$

$$v(t) = v_0 - \frac{eE_0}{m\omega} (1 - \cos \omega t)$$

||

$$\frac{dx(t)}{dt}$$

$$\int_0^t dx$$

$$\int_0^t \frac{dx(t)}{dt} dt = x(t) - x(0) = x(t)$$

$$\int_0^t \left(v_0 - \frac{eE_0}{m\omega} \right) + \frac{eE_0}{m\omega} \cos \omega t \, dt$$

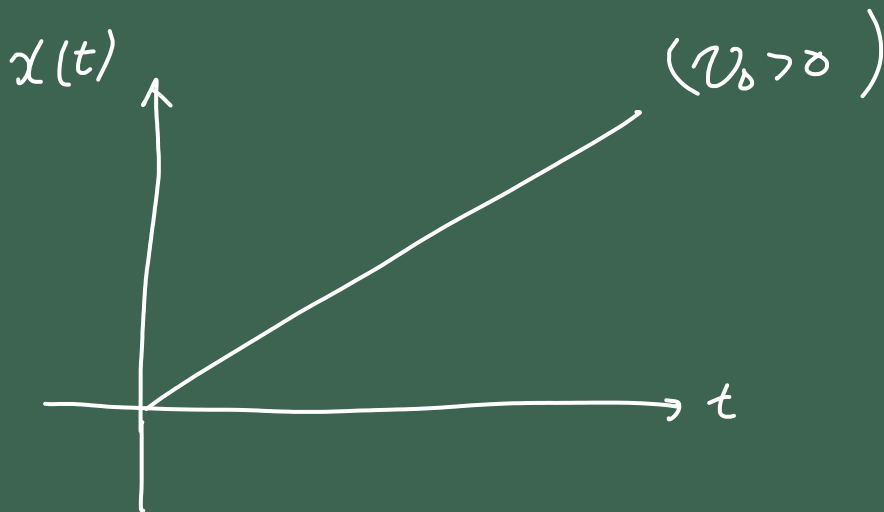
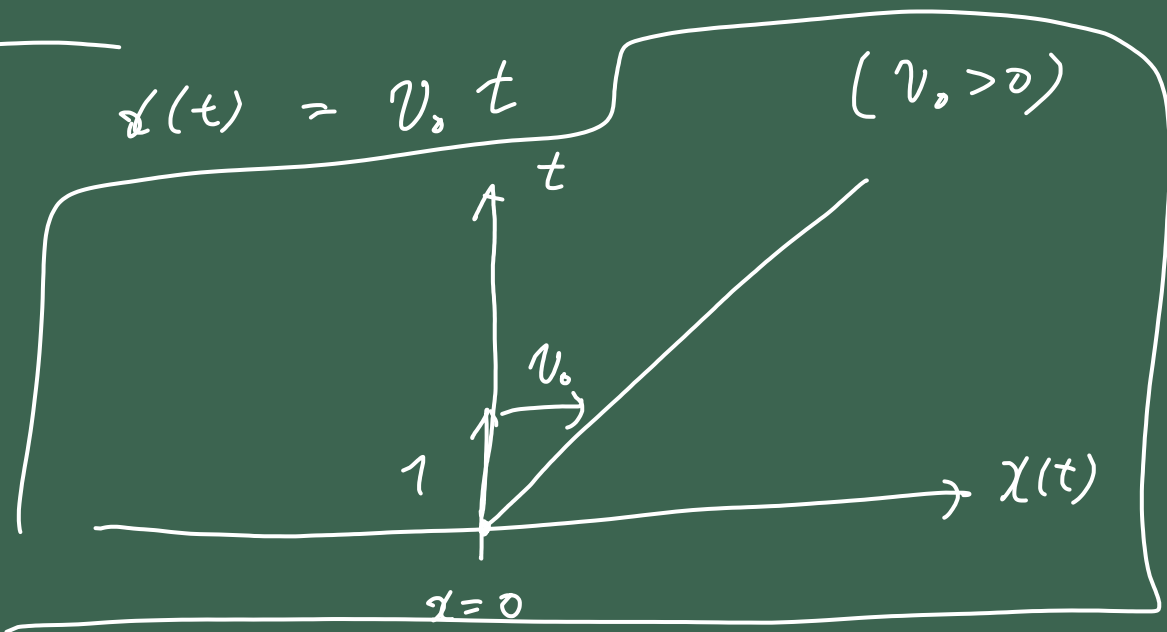
$$= \left[\left(v_0 - \frac{eE_0}{m\omega} \right) t + \frac{eE_0}{m\omega^2} \sin \omega t \right]_0^t$$

$$= \left(v_0 - \frac{eE_0}{m\omega} \right) t + \frac{eE_0}{m\omega^2} \sin \omega t$$

(11)

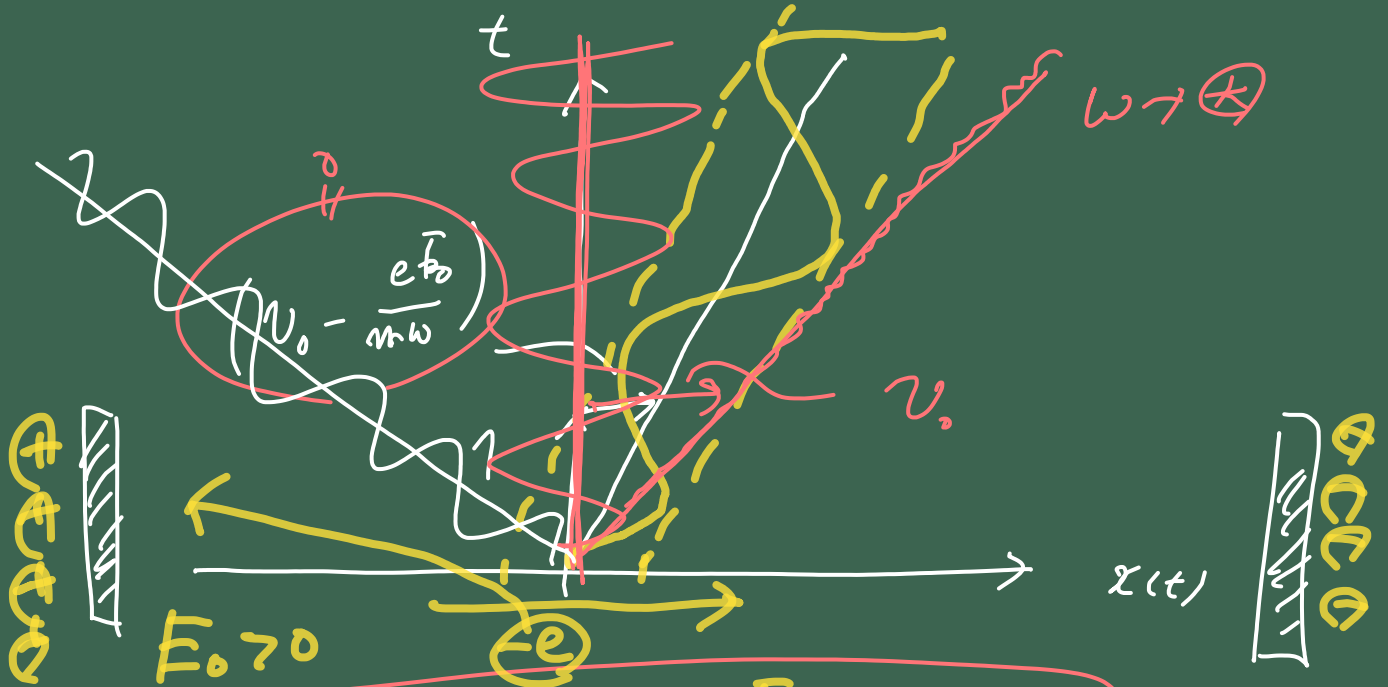
$$(5) \quad x(t) = \left(v_0 - \frac{eE_0}{m\omega} \right) t + \frac{eE_0}{m\omega^2} \sin \omega t$$

$$\uparrow E_0 = 0$$



$$E_0 \neq 0, \quad \omega \ll \frac{v_0}{c}$$

$$x(t) = \left(v_0 - \frac{eE_0}{m\omega} \right) t + \frac{eE_0}{m\omega^2} \sin \omega t$$



$$\omega \rightarrow \pi \quad v_0 - \frac{eE_0}{m\omega} \rightarrow v_0$$

$$\frac{eE_0}{m\omega^2} \rightarrow 0$$

$$v_0 - \frac{eE_0}{m\omega} = 0$$

$$(5) \quad \omega = \frac{eE_0}{m v_0} \quad (=)$$

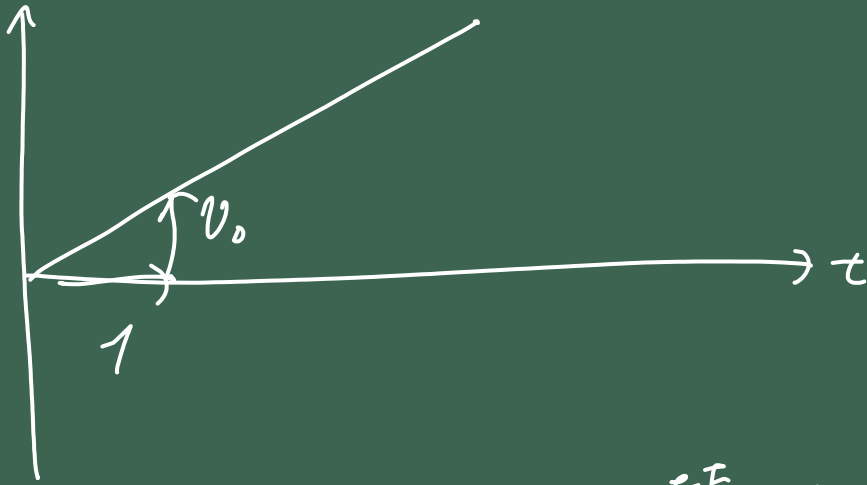
$$v_0 \oplus \rightarrow \omega \oplus$$

$$v_0 \oplus \rightarrow \omega \oplus$$

$$E_0 = 0$$

 $x(t)$

$$x(t) = v_0 t$$

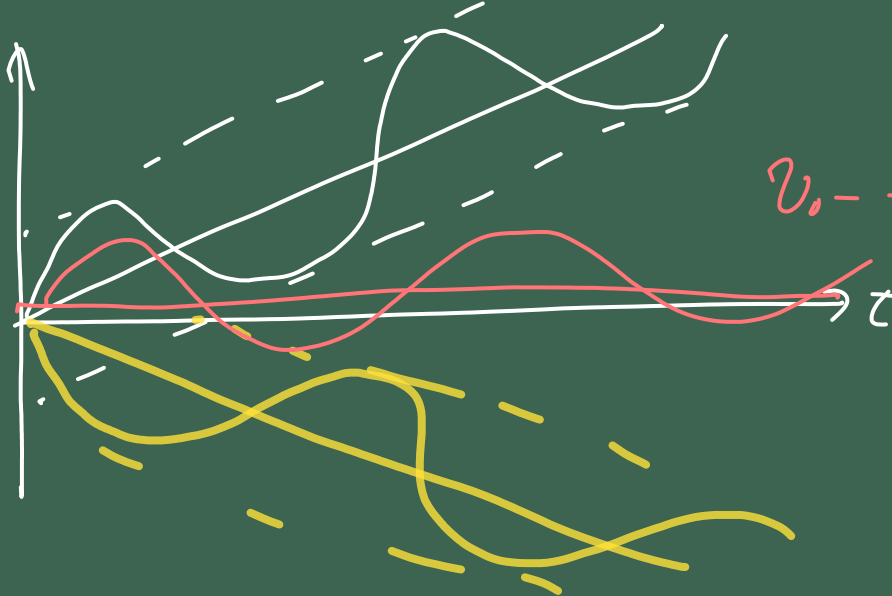


$$v_0 - \frac{eE}{m\omega} > 0$$

$$E_0 \neq 0$$

 $x(t)$

$$\left(v_0 - \frac{eE}{m\omega}\right) t$$

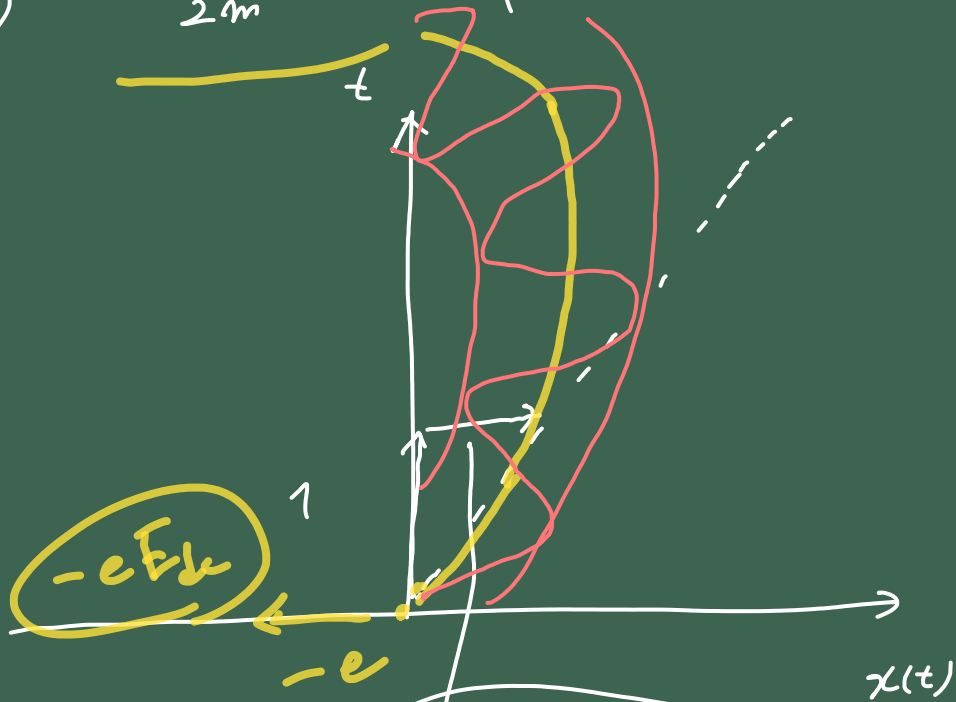


$$v_0 - \frac{eE}{m\omega}$$

$$v_0 - \frac{eE}{m\omega} < 0$$

$$-\frac{eF_{dc}}{m} \int_0^t t \, dt = -\frac{eF_{dc}}{2m} t^2$$

$$x_1(t) = -\frac{eF_{dc}}{2m} t^2 + \left(v_0 - \frac{eF_{ac}}{m\omega} \right) t + \frac{eF_{ac}}{m\omega^2} \sin \omega t$$



$$F_{ac}, F_{dc} > 0$$

$$v_0 - \frac{eF_{ac}}{m\omega} > 0$$

